Overload Protection Equipment

TORQUE LIMITERS

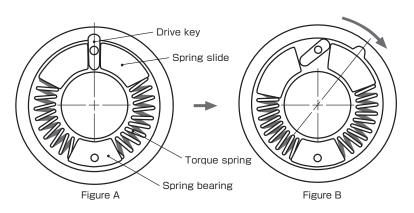
Semiconductor manufacturing equipment, textile machinery, printing machinery

Detecting an Overload Reliably and Taking Appropriate Action to Protect the Machine against Overload

This torque limiter detects an overload and disconnects the input side and the output side immediately to protect the machine. Because it is the one-position engagement type, when the overload is removed, the input and output are automatically connected with the same torque in the same indexing position. In contrast to the friction type, this type can be used even in adverse environments.





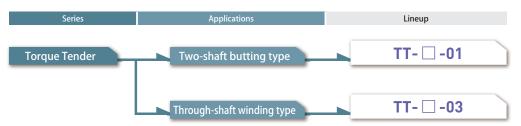


- 1. Normally the drive key is engaged with the groove of the housing to transmit torque. (Figure A)
- 2. If an overload is applied, the drive key is tilted against the force of the torque spring and disconnected from the groove of the housing to disconnect the input side and the output side. (Figure B)
- 3. When the input side and the output side are returned to the original indexing position after removing the overload, the operation can be restarted with the torque that was set originally.
- 4. The normal and reverse rotation torque can be changed by independently connecting normal and reverse rotation torque springs. (Please contact Miki Pulley for details.)

SPEED CHANGERS

TORQUE LIMITERS

Available Models



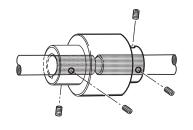
* Torque tender is the name of Miki Pulley's overload protection equipment

TT- - -01 Types (Two-shaft Butting Type)

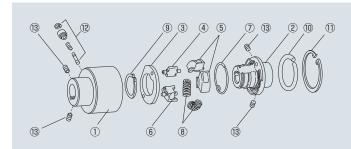
The two-shaft butting type is made by inserting two shafts from both ends (housing and hub) of the torque tender and securing them with set screws to transmit power and protect the machine against overload.

The two-shaft butting type can also be used as a flexible coupling.

- Set torque: 0.2 to 200 N · m
- Applied shaft diameter: 8 to 50 mm







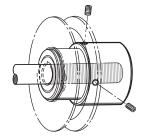
- ① Housing ② Hub ③ Hub ring ④ Drive key ⑤ Spring slide ⑥ Spring bearing
- 7 Reset spring 8 Torque spring
- 9 Stop ring ® Stop ring washer
- ① Stop ring ② Signal pin (option)
- 3 Set screws (included)

TT- -03 Types (Winding Type)

The winding type is made by inserting the shaft into the inside (hub) of the torque tender and attaching a pulley, sprocket, or gear to the outside of the housing to transmit power and protect the machine against overload.

The shaft is designed to be secured at the center of the main unit so it can be attached even if its end is structured as a through-shaft

- \bullet Set torque: 0.2 to 200 N \cdot m
- Applied shaft diameter: 8 to 45 mm





MODELS

TT

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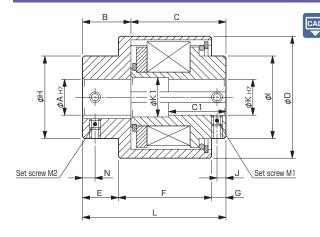
- ① Housing ② Hub ③ Hub ring ④ Drive key ⑤ Spring slide ⑥ Spring bearing
- 7 Reset spring 8 Torque spring
- Stop ring Stop ring washer
- ① Stop ring ② Signal pin (option)
- (included) (in Oilless metal
- 15 Outer diameter key (included)
- (6) Stop ring (included)

Specifications

	Size				Set tor	que value	[N·m]		Misalignment						
Model					S	pring colo	r				Parallel	Angular	Max. rotation speed	Moment of inertia	Mass
		Colorless	Blue	Red	Yellow	White	Gray	Green	Brown	Colorless	[mm]	[°]	[min-1]	[kg·m²]	[kg]
TT-1X-01	1X	0.2	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	0.2	0.5	1800	0.06×10^{-3}	0.3
TT-2-01	2	1	2	3	4	5	6	7	8	10	0.2	0.5	1800	0.26×10^{-3}	0.7
TT-2X-01	2X	2	3	5	8	10	12	15	18	20	0.2	0.5	1800	0.52×10^{-3}	1.0
TT-3-01	3	5	8	10	15	20	25	30	35	40	0.2	0.5	1800	1.23×10^{-3}	1.5
TT-3X-01	3X	10	16	20	30	40	50	60	70	80	0.2	0.5	1800	1.94×10^{-3}	2.7
TT-4X-01	4X	20	30	50	80	100	120	150	180	200	0.2	0.5	500	14.8×10^{-3}	6.3

^{*} The set torque values in the table above are those when the rotation speed is 1500 min⁻¹. The operation torque varies depending on the operating rotation speed. Please check P563.
* If you need durability for the torque values in the area, select a larger size.

Dimensions



		Unit [mm]
Size	Shaft bore dimensions in compl	iance with the new JIS standards
Size	Α	K
1X	10 • 11 • 12 • 14	10 • 11 • 12
2	11 • 12 • 14 • 15 • 16 • 18 • 19 • 20	11 • 12 • 14 • 15 • 16
2X	14 • 15 • 16 • 18 • 19 • 20 • 22 • 24	14 • 15 • 16 • 18 • 19
3	18 • 19 • 20 • 22 • 24 • 25 • 28 • 30	18 • 19 • 20 • 22 • 24 • 25
3X	18 • 19 • 20 • 22 • 24 • 25 • 28 • 30	18 • 19 • 20 • 22 • 24 • 25
4X	19 • 20 • 22 • 24 • 25 • 28 • 30 • 32	19 • 20 • 22 • 24 • 25 • 28 • 30
47	35 • 38 • 40 • 42 • 45 • 48 • 50	32 • 35 • 38 • 40 • 42 • 45

Unit [mm]

Size	Shaft bore dimensions in compliance with the old JIS standards $$									
Size	Α	K								
1X	8 • 10 • 11 • 12 • 14	8 • 10 • 11 • 12								
2	11 • 12 • 14 • 15 • 16 • 18 • 19 • 20	11 • 12 • 14 • 15 • 16								
2X	14 • 15 • 16 • 18 • 19 • 20 • 22 • 24	14 • 15 • 16 • 18 • 19 • 20								
3	18 • 19 • 20 • 22 • 24 • 25 • 28 • 30	18 • 19 • 20 • 22 • 24 • 25								
3X	18 • 19 • 20 • 22 • 24 • 25 • 28 • 30	18 • 19 • 20 • 22 • 24 • 25								
4X	19 • 20 • 22 • 24 • 25 • 28 • 30 • 32	19 • 20 • 22 • 24 • 25 • 28 • 30								
48	35 • 38 • 40 • 42 • 45 • 48 • 50	32 • 35 • 38 • 40 • 42 • 45								

^{*} There is no keyway for bore diameter ø8 mm.

^{*} For the bore drilling standards, see P562.

															Unit [mm]
Size	K1	В	С	C1	D	E	F	G	Н	1	J	L	N	M1	M2
1X	12.5	20	30	23	42	15	30	5	25	22	3	50	6	2-M4	2-M4
2	16.5	25	41	32.5	55	20	35	11	35	32	5	66	7	2-M5	2-M5
2X	20.5	31	45	34	65	25	40	11	40	38	5	76	8	2-M5	2-M5
3	25.5	38	53	40	75	30	50	11	45	45	5	91	10	2-M6	2-M6
3X	25.5	36	85	41	75	30	80	11	45	45	6	121	10	2-M6	2-M6
4X	_	46	95	-	120	35	90	16	80	80	8	141	12	2-M10	2-M10

How to Place an Order

TT-2X-01-14N-19H-10NM-P Size Option Blank: None
P: Equipped with a signal pin Type — 01: Two-shaft butting Set torque

* Contact Miki Pulley for assistance in changing the set torque Contact MIKI Pulley for assistance in char for normal or reverse operation. Key specifications
Blank: Compliant with the old JIS standards (class 2)
H: Compliant with the new JIS standards
N: Compliant with the new motor standards Housing bore diameter (ϕ A) -Key specifications
Blank: Compliant with the old JIS standards (class 2)
H: Compliant with the new JIS standards
N: Compliant with the new motor standards Hub bore diameter (φK)

TT- -03 Types

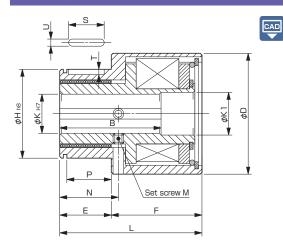
Specifications

					Set to	orque value [N∙m]						
Type	Size					Spring color					Max. rotation speed	Moment of inertia	Mass
		Colorless Blue Red Yellow White Gray Green Brown Colorless							[min-1]	[kg·m²]	[kg]		
TT-1X-03	1X	0.2	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	1800	0.09×10^{-3}	0.4
TT-2-03	2	1	2	3	4	5	6	7	8	10	1800	0.31×10^{-3}	0.8
TT-2X-03	2X	2	3	5	8	10	12	15	18	20	1800	0.66×10^{-3}	1.1
TT-3-03	3	5	8	10	15	20	25	30	35	40	1800	1.59×10^{-3}	1.7
TT-3X-03	3X	10	16	20	30	40	50	60	70	80	1800	2.43×10^{-3}	3.0
TT-4X-03	4X	20	30	50	80	100	120	150	180	200	500	15.8×10^{-3}	6.5

* The set torque values in the table above are those when the rotation speed is 1500 min⁻¹. The operation torque varies depending on the operating rotation speed. Please check P563.
* If you need durability for the torque values in the area, select a larger size.

TORQUE LIMITERS

Dimensions



	Unit [mm]
Size	$Shaft bore \ dimensions \ in \ compliance \ with \ the \ new \ JIS \ standards$
Size	К
1X	10 • 11 • 12
2	11 • 12 • 14 • 15 • 16
2X	14 • 15 • 16 • 18 • 19
3	18 · 19 · 20 · 22 · 24 · 25
3X	18 · 19 · 20 · 22 · 24 · 25
4X	19 • 20 • 22 • 24 • 25 • 28 • 30 • 32 • 35 • 38 • 40 • 42 • 45

Unit [mm]

Size	$Shaft bore \ dimensions \ in \ compliance \ with \ the \ old \ JIS \ standards$
Size	К
1X	8 • 10 • 11 • 12
2	11 • 12 • 14 • 15 • 16
2X	14 • 15 • 16 • 18 • 19 • 20
3	18 · 19 · 20 · 22 · 24 · 25
3X	18 · 19 · 20 · 22 · 24 · 25
4X	19 • 20 • 22 • 24 • 25 • 28 • 30 • 32 • 35 • 38 • 40 • 42 • 45

* There is no keyway for bore diameter ø8 mm. * For the bore drilling standards, see P562.

													Unit [mm]
Size	K1	В	D	E	F	Н	N	L	P	S	Т	U	M
1X	12.5	34	42	20	35	30	25	55	16	14	2.5	4	2-M4
2	16.5	38	55	25	40	40	30	65	20	18	3	5	2-M5
2X	20.5	40	65	25	45	45	31	70	20	18	3	5	2-M5
3	25.5	52.5	75	35	55	60	45	90	30	28	4	7	2-M6
3X	25.5	75	75	35	90	60	45	125	30	28	4	7	2-M6
4X	46	100	120	50	90	85	57	140	45	40	4.5	12	2-M8

^{*} The outer diameter key (old JIS class 2) and stop ring are included accessories.

MODELS

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How to Place an Order

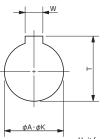
TT-2X-03-19H-10NM-P Option Blank: None P: Equipped with a signal pin Type ____ 03: Winding Set torque
*Contact Miki Pulley for assistance in changing the set torque Hub bore diameter (φK)for normal or reverse operation. Key specifications
 Blank: Compliant with the old JIS standards (class 2)
 H: Compliant with the new JIS standards
 N: Compliant with the new motor standards

Web code

Torque Limiters

Standard Hole-Drilling Standards

- The set screws are included with the product.
- For standard bore drilling dimensions other than those specified, please contact Miki Pulley. (A bore may not be able to be drilled for some hub sizes.)



Unit	[mm]
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									Models compliant with the new motor standards					
	ls compliant witl	h the old JIS stand			odels compliant	with the new JIS			lels compliant w	ith the new moto				
Nominal bore diameter	Bore diameter øA/øK	Keyway width W	Keyway height T	Nominal bore diameter	Bore diameter øA/øK	Keyway width W	Keyway height T	Nominal bore diameter	Bore diameter øA/øK	Keyway width W	Keyway height T			
Tolerance	H7	E9	+ 0.5	Tolerance	H7	Н9	+ 0.5 0	Tolerance	G7	H9	+ 0.5 0			
8	8 + 0.015	_	-	_	_	_	_	_	_	_	_			
10	10 + 0.015	4 + 0.050 + 0.020	11.5	10 H	10 + 0.015	4 + 0.030	11.8	_	-	-	-			
11	11 + 0.018	4 + 0.050 + 0.020	12.5	11 H	11 + 0.018	4 + 0.030	12.8	_	_	_	_			
12	12 + 0.018	4 + 0.050 + 0.020	13.5	12 H	12 + 0.018	4 + 0.030	13.8	_	_	_	_			
14	14 + 0.018	5 + 0.050 + 0.020	16.0	14 H	14 + 0.018	5 + 0.030	16.3	14 N	14 + 0.024 + 0.006	5 + 0.030	16.0			
15	15 + 0.018	5 + 0.050 + 0.020	17.0	15 H	15 + 0.018	5 + 0.030	17.3	_	-	-	_			
16	16 + 0.018	5 ^{+ 0.050} + 0.020	18.0	16 H	16 + 0.018	5 + 0.030	18.3	_	_	_	_			
18	18 + 0.018	5 ^{+ 0.050} + 0.020	20.0	18 H	18 + 0.018	6 + 0.030	20.8	_	_	_	_			
19	19 + 0.021	5 ^{+ 0.050} + 0.020	21.0	19 H	19 + 0.021	6 + 0.030	21.8	19 N	19 + 0.028 + 0.007	6 + 0.030	21.5			
20	20 + 0.021	5 ^{+ 0.050} + 0.020	22.0	20 H	20 + 0.021	6 + 0.030	22.8	_	_	_	_			
22	22 + 0.021	7 ^{+ 0.061} + 0.025	25.0	22 H	22 + 0.021	6 + 0.030	24.8	_	_	_	_			
24	24 + 0.021	7 + 0.061 + 0.025	27.0	24 H	24 + 0.021	8 + 0.036	27.3	24 N	24 + 0.028 + 0.007	8 + 0.036	27.0			
25	25 + 0.021	7 + 0.061 + 0.025	28.0	25 H	25 + 0.021	8 + 0.036	28.3	_	_	_	_			
28	28 + 0.021	7 + 0.061 + 0.025	31.0	28 H	28 + 0.021	8 + 0.036	31.3	28 N	28 + 0.028 + 0.007	8 + 0.036	31.0			
30	30 + 0.021	7 + 0.061 + 0.025	33.0	30 H	30 + 0.021	8 + 0.036	33.3	_	_	_	_			
32	32 + 0.025	10 + 0.061 + 0.025	35.5	32 H	32 + 0.025	10 + 0.036	35.3	-	_	_	_			
35	35 ^{+ 0.025}	10 + 0.061 + 0.025	38.5	35 H	35 + 0.025	10 + 0.036	38.3	_	_	_	_			
38	38 + 0.025	10 + 0.061 + 0.025	41.5	38 H	38 + 0.025	10 + 0.036	41.3	38 N	38 + 0.034 + 0.009	10 + 0.036	41.0			
40	40 + 0.025	10 + 0.061 + 0.025	43.5	40 H	40 + 0.025	12 + 0.043	43.3	_	_	_	_			
42	42 + 0.025	10 + 0.061 + 0.025	45.5	42 H	42 + 0.025	12 + 0.043	45.3	42 N	42 + 0.034 + 0.009	12 + 0.043	45.0			
45	45 + 0.025	12 + 0.075 + 0.032	48.5	45 H	45 + 0.025	14 + 0.043	48.8	_	_	_	_			
48	48 + 0.025	12 + 0.075 + 0.032	51.5	48 H	48 + 0.025	14 + 0.043	51.8	48 N	48 + 0.034 + 0.009	14 + 0.043	51.5			
50	50 + 0.025	12 + 0.075	53.5	50 H	50 + 0.025	14 + 0.043	53.8	-	_	_	_			

Optional Signal Pin

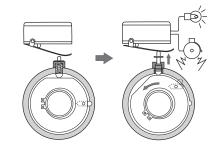
Unattended or remotely controlled machines and equipment require equipment that detects an overload and automatically switches off the power or sounds a warning alarm.

An overload can be detected by connecting the signal pin to the torque tender.

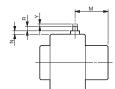
When an overload is detected, the input side and the output side are disconnected and the cam mechanism of the torque tender hub pushes the signal pin out in the radial direction. This can be used to switch off the power or sound a

Be sure to use the housing as the input side.

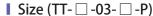
The standard product cannot be modified to connect the signal pin. If you need to connect the signal pin, add -P to the end of the model when you order the

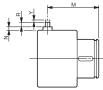


I Size (TT- □ -01- □ -P)



				Unit [min]
Size	M	Υ	R	N
1X	24	1.5	6.5	5.5
2	29	2.5	5	4.5
2X	36	2.5	5	4.5
3	43	2.5	5	4.5
3X	42	2.5	5	4.5
4X	55	2.5	5	2





				Unit [mm]
Size	M	Υ	R	N
1X	47	1.5	6.5	5.5
2	56	2.5	5	4.5
2X	60	2.5	5	4.5
3	79	2.5	5	4.5
3X	114	2.5	5	4.5
4X	125	2.5	5	2

Items Checked for Design Purposes

I Precautions for Use

- 1. Touching the product in operation with your hand or fingers may cause injury. Be sure to install a safety cover to prevent a hazard.
- 2. If the overload protection equipment is activated, the driving side and the driven side of the product are disconnected completely. Be sure to install a safety mechanism such as a safety brake to prevent a hazard.
- 3. The product is designed as overload protection equipment and is not designed as torque detection equipment. Never use it as torque detection equipment. Doing so may cause problems.
- 4. If the operation is continued while the overload protection mechanism is activated, the product may generate heat. If nothing is done, the product may be damaged and the equipment may be adversely affected. Be sure to install detection equipment, and if the overload protection mechanism is activated, immediately stop the operation of the equipment.
- 5. Do not use the product in a location where it may be exposed to corrosive gases and chemicals. The product is not waterproof so do not use it in a location where it may be exposed to water.
- 6. Do not use the product outside the operating temperature range of -40°C and 120°C .
- 7. All torque springs are inserted by us before delivery. If you want the set torque to be changed, please consult with our sales office. Do not disassemble and replace the spring.

- 8. Never use the product with a rotation speed other than the design one. If you use it with a rotation speed other than the design one, the driving side and the driven side will not be disconnected under a load under which you want to activate the overload protection mechanism, or will be disconnected under a load less than the one under which you want to activate the overload protection mechanism.
- If the torque tender is activated by an overload, immediately stop the operation. Check to make sure that the main power of the equipment is switched off and then remove the cause for the overload on the driven side. When you connect the driving side and the driven side for recovery, manually rotate the driving side by applying a torque of more than 55% of the set torque at 1500 min⁻¹ to the driven side. Before restarting the operation, be sure to perform a start-up inspection
- 10. The mounting tolerance of the TT- \square -01 type is 0.2 mm or less for the parallel misalignment and 0.5° or less for the angular deflection.
- 11. When you use an optional signal pin, pay attention to the following points.

Selecting the Model and Set Torque

of the characteristics of the torque tender.

1500 min⁻¹ using the following expression.

- Make sure that the **housing is the input side**.

 Make sure that detection switches are installed in two positions away from each other at 120° or more in the rotation direction. An overload may not be detected with a single switch
- * The quality of the signal pin is good enough, but please install an additional detector other than the

The operation torque changes as shown in the figure below as a result

The set torque values of the torque tender are those when the rotation

speed is 1500 min⁻¹. Accordingly, you need to read torque coefficient

a at the rotation speed of the shaft to which the torque tender is

connected from the figure below, and convert it to the set torque at

12. There is backlash.

 $Ts = \frac{T}{a}$

and test run.

Selection

■ Determining the Operation Torque Value

Determine the operation torque value T of the torque tender based on the mechanical strength, load, and other conditions.

If the operation torque cannot be determined based on the above conditions, it can be calculated with an expression of the rated output of the drive unit and the rotation speed of the shaft to which the torque tender is connected.

$$T = K \times \frac{9550 \times P}{n}$$

- T: Operation torque [N · m]
- K: Service factor
- P: Drive unit rated output [kW]
- n: Torque tender rotation speed [min - 1]

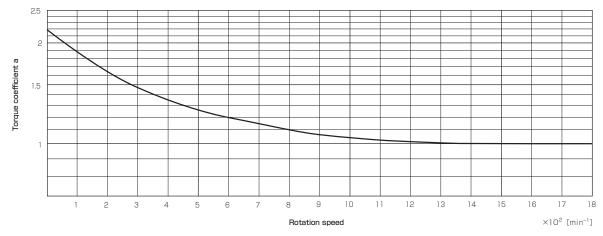
T: Operation torque [N · m] a: Torque coefficient

Ts: Set torque at 1500 min $^{-1}$ [N \cdot m]

From the specification table, select the size whose set torque value is closest to Ts that was calculated with the expression above.



Directly connected to the motor	2.0 ~ 2.5	
After changing speed	1.75 ~ 2.0	
After deceleration	1.25 ~ 1.50	
Rotation speed 25 min ⁻¹ or less	1.25	



 $^{^{\}ast}~$ Use size 4X at a rotation speed equal to or less than 500 min $^{-1}.$

SPEED CHANGERS

TORQUE LIMITERS

MODELS